

STAR PRONNAX PRODUCT USER MANUAL





The Star Pro Max is our top-selling model, designed for versatile cutting applications. While it is excellent for woodworking tasks like cutting MDF, it also has the capability to precisely cut through a variety of non-wood materials, including acrylic, PVC, aluminum, and even copper.

This is an auto tool changing machine that features a linear tool magazine, wich allows it to accomplish complicated jobs that require different patterns of tools, changing the tools automatically in a single operation.







PREFACE

Thank you for purchasing our product!

Please read the following notes carefully after receiving your machine:

Read the following pre installation precautions and check whether the installation environment of the machine is suitable to avoid unnecessary trouble for your installation and use. 2

Check the appearance and packaging of the machine to see if there is any damage.

* Some technical parameters involved in this manual are subject to change without further notice.



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1. Delivery of the machine

To ensure that your machine can be used normally, please read the following before delivering the machine:

For the convenience of loading and unloading, please prepare a forklift before unloading the machine (recommended to be 3 tons and above).



* Due to the large size of the machine, we will remove the gantry and other components when shipping.

- Place the machine tool in the designated position and level the four legs of the machine tool. (Note: The four legs must be leveled and cannot be deflected or suspended in the air).
- 2) The installation environment requires no water droplets, steam, or oily dust.
- 3) The ground is flat, clean, solid and free of vibrations.
- 4) There is no electromagnetic interference nearby.
- 5) The operating ambient temperature is 5°C ~ 35°C. When the ambient temperature exceeds 35°C, please install ventilation facilities. Relative humidity environment: 30% ~ 75%.

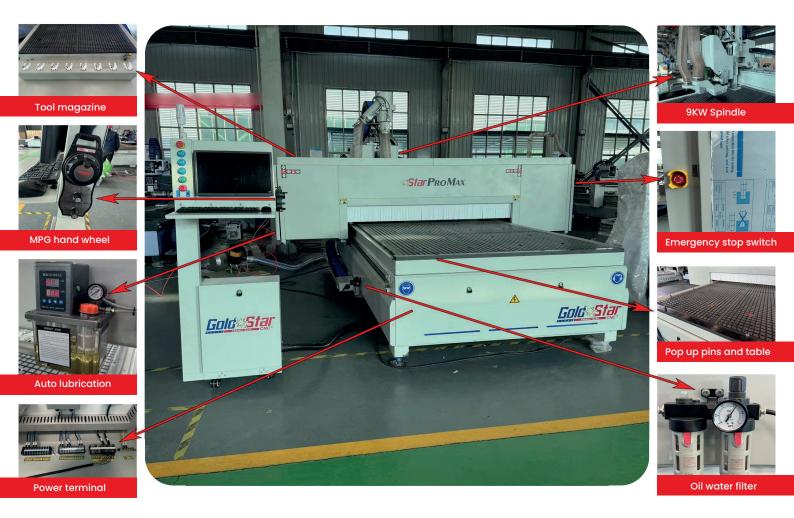


- 6) The input voltage is AC380V/50/60Hz or AC220V/50/60Hz. Please connect the voltage indicated on the nameplate according to the instructions on the machine nameplate.
- 7) Some machines will be packed in wooden boxes with plastic packaging inside. Please check the general condition of the machine before unpacking it.
- 8) There may be wood dust or lubricating oil inside the machine, which is generated during the factory testing process.
- 9) Please ensure there is enough space to place the machine, and reserve an area for vacuum cleaners, vacuum pumps, control cabinets and other tools that may be carried.
- 10) Please refer to the machine parameters, consider the weight of the site environment and electrical load, and whether the on site wiring meets the requirements.
- 11) Regarding the assembly of the machine, the weight of the machine is very heavy and requires 2 or more people to complete it. During the assembly process, you need to pay attention to personal safety and use appropriate tools to assemble the mechanical and electrical components of the machine.
- 12) The wiring of the line connection must be correct and firm. The connecting line must not be damaged, squeezed, or twisted, otherwise a short circuit or an open circuit may occur. The power plug must not be plugged or unplugged while the power is on. Keep hands dry before plugging or unplugging the plug to prevent safety accidents. Personnel involved in wiring must have corresponding abilities.



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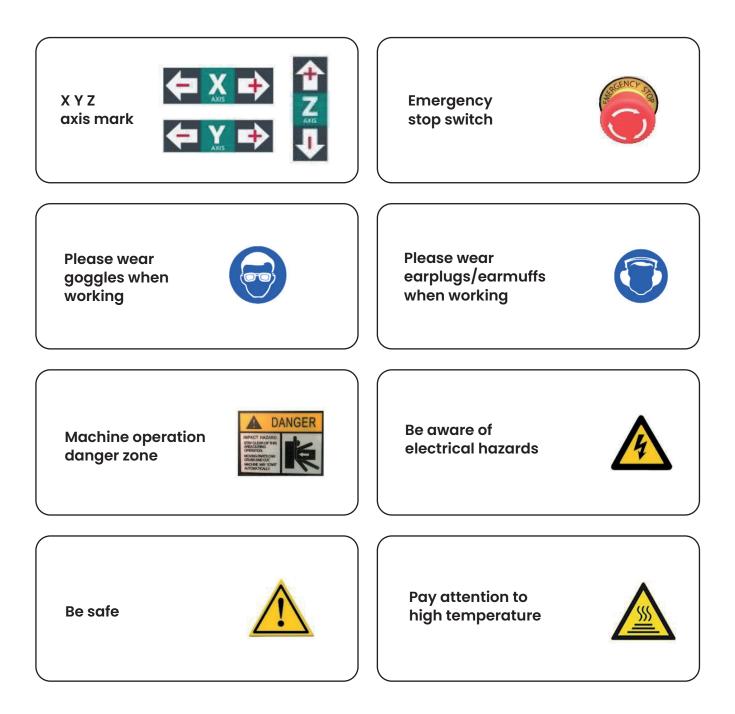
2. Machine overview



* For reference only, please refer to the actual situation.

3. About the machine identification

There are many technical signs and safety signs on our machines. Please read the following overview. The information they contain is to ensure the safety of the machine operator and the stable and normal operation of the machine itself. (The color of the axial mark may be differen t, please refer to the actual machine).



4. Important safety instructions

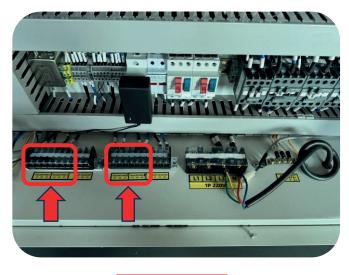
Before assembling this machine, please read this safety operation instruction carefully. Failure to pay attention to the following instructions may lead to electric shock, fire and other serious safety accidents. Do not change the factory settings of this machine at will. This machine is designed for specialized industries. Do not use it for purposes outside other industries, as this may cause machine failure; if you have any other questions, please contact us.

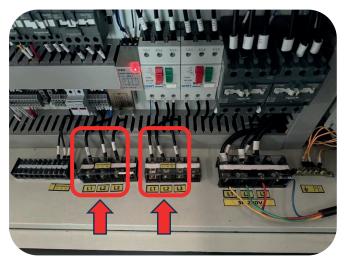
- The machine itself has certain noise and safety hazards. Necessary safety protection measures cannot be ignored. Machine operators must undergo strict training and need to concentrate during operation. Pay attention to personal safety and machine safety du ring operation.
- 2) The power supply voltage requirement of the machine itself is 380V/220V. Only professional personnel are allowed to perform electrical installation and maintenance work. Check the grounding condition of the machine, and the power supply needs to be cut off before installation and maintenance.
- 3) The cutter must be installed and clamped to keep the cutter sharp. A dull cutter will reduce the quality of the engraving and overload the motor.
- 4) The size of the processed materials should not exceed the machining range. Please cut off the power when not in use for a long time. There must be professional guidance when moving the machine.
- 5) Be sure to pass the water before using the water cooled spindle.
- 6) Do not put your fingers into the working range of the tool, and do not remove the engraving head for other purposes. Materials containing asbestos must not be processed
- 7) Please pay attention to the various warning signs on the machine and make correct judgments
- 8) Do not wear clothes that may get entangled in the machine (the high speed rotation of the spindle will cause danger), do not be in the danger zone of the machine, and use the correct tools to complete the corresponding operations of the machine.
- 9) Avoid damage to the power cord caused by moisture or external foreign objects.

5. Installation Notes

5.1. Vacuum pump installation

- After receiving the machine, take the vacuum pump out of the package and fix the steel wire tube at the air inlet of the filter with a tightening tool.
- Open the cover of the motor and connect it to the power supply, and connect the other end to the wiring of the vacuum pump controlled by the engraving machine. Refer to the figure below to connect the power supply (the voltage and terminals are subject to the actual machine).
- Pay attention to the cleaning of the filter during daily use.



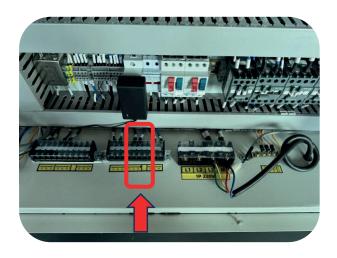


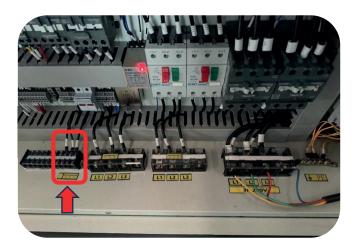
1P 220 V

3P 220 V

5.2. Dust collector installation

- Take the vacuum cleaner out of the package, install it according to the vacuum cleaner instructions, and place it stably.
- Connect the power supply to the vacuum cleaner, and connect one end of the power supply to the electrical box vacuum cleaner connection. Refer to the figure below to connect the power supply (the terminal is subject to the actual machine). Connect one end of the vacuum hose to the machine's vacuum hood and the other end to the vacuum cleaner.





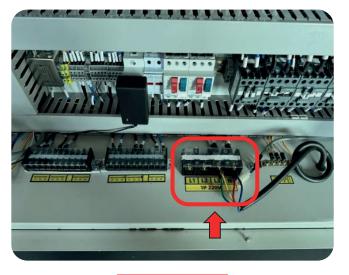


3P 220 V

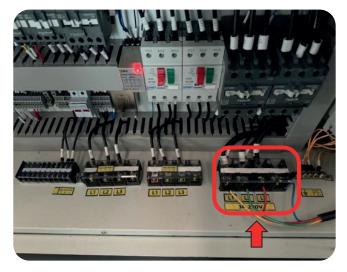
5.3. Power and air supply installation

5.3.1. Power supply

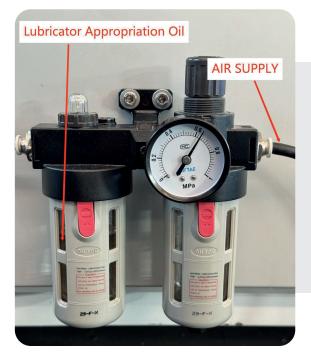
 Refer to the diagram below to connect the power supply (the voltage and terminals are subject to the actual machine). When connecting the power cord, be sure to pay attention. The power cords with wire numbers L1, L2, and L3 are live wires, the neutral wire is N, and the ground wire is PE. , please confirm that the wire numbers are connected accordingly, otherwise a short circuit will occur and burn the machine; the ground wire must be connected to ensure safe operation.







3P 220 V



5.3.2. Air source

A clean air source should be connected and the air pressure should be maintained at 0.6 0.8Mpa.

5.4. Installation of other accessories

After all accessories are installed, you need to check whether the accessories are installed correctly and whether the gaps are appropriate.



6. Preparation and operating instructions before machine operation

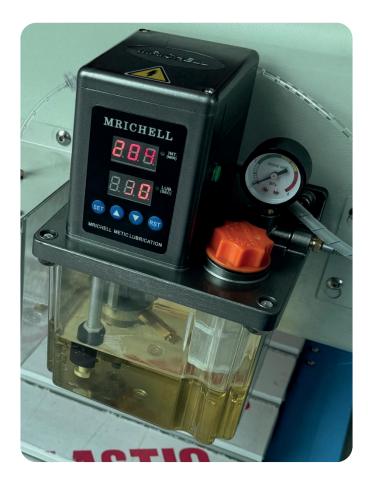
5.5. Check air source

After connecting the air source, the air pressure increases to 0.6 - 0.8 Mpa (The system will sound an alarm if the pressure is too small or too large).



5.6. Check automatic lubrication

Automatic lubrication will replenish oil every time the machine is turned on and every 240 minutes after starting the machine. Replenish oil for 30 seconds each time (please do not turn on and off the power frequently. Automatic lubrication will replenish oil every time you turn on the machine). The parameters of automatic lubrication have been set by our technicians when the mach ine leaves the factory. Please do not change the settings at will. Please also pay attention to regular inspection and cleaning. If you have any questions, please contact us in time.





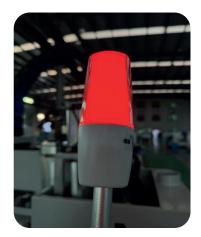
5.7. Power on

Press the corresponding start button on the control chassis to turn on the power and start the control system.

After the power is turned on, you can judge the current status of the machine by observing the signal light. For example, the execution of processing programs, MDI mode, etc. will be displayed in green, the standby display will be displayed in orange, the alarm or pressing the emergency stop switch will be displayed in red, etc., in conjunction with the software status bar. Determine current machine status.





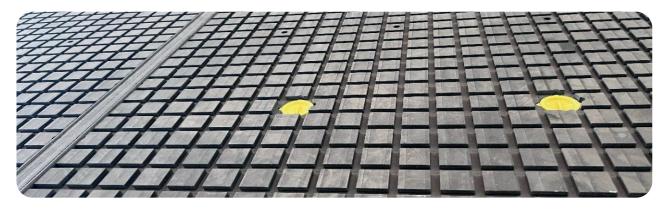


5.8. Material fixation

1. The vacuum adsorption table is divided into 6 areas . Each valve corresponds to the corresponding area of the work surface. The corresponding area can be opened according to the material selection.



2. Use the negative pressure of the vacuum suction table to adsorb the material to the surface of the vacuum suction table.



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 Select the required positioning cylinder button from the operation panel to raise the positioning cylinder at the corresponding position.



6. Operating system instructions

If you are using this type of system for the first time, please read this manual carefully and use the handwheel mode to **operate with caution***; if you have relevant experience, please quickly find the information you need through the catalog.

* Because it involves modified parameter settings, here we only introduce some common functions and basic operations of the machine to prevent misoperation caused by introducing too many functions and modifying the set factory parameters. However, this will be used in actual use. Please forgive me for the functions not introduced in the manual or the need to modify some parameters. If you need to use the functions not introduced in this manual or modify the parameters, please use the handwheel to guide the operation carefully according to the actual situation or perform it under the guidance of a technical engineer. Operation, if you have any questions or suggestions, please contact us in time.

Mechanical coordinate system

The mechanical coordinate system is a fixed coordinate system that has been set by our technical engineers, and its coordinate origin is always relative to the fixed position of the machine tool. Every time the power is cut off and restarted, or after an emergency stop of the system, the machine needs to return to mechanical zero.

Workpiece coordinate system

The workpiece coordinate system is a new coordinate system established by selecting a known point on the workpiece as the origin (also called the workpiece origin).

6.1. Main screen introduction

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		0.000	-	0.000	
<u> </u>		0.000 0.000 0.000			Inc JOG MPG
Z		0.000	Absolute x	-10 000	HOME
			Y Z	-10.000 -10.000 10.000	
					MPG SIM
					S.B.K
			Dist. To Go	0.000	Main
	⁰⁰ % S	24000 RPM 100	Z	0.000 0.000 0.000	Set Tool
0.0 mm/min (Act Run Time 0 : 0 :	0 Part Count	24000 RPM (Actua 0 T 1	u)		Set Drill
				1	
	eady Hann	Cycle	a Start Feed Hold	Reset	Alarm
< F1 Operator Panel F2 Program F3	Offset/ Setting F4 Monitor	F5 Maintain F6	File Manager F7 Fast D	Diag F8 Sys Ad	lmin >>

Screen section description:

Serial number	Screen content	No matter how the screen is switched, the following information will always be on the background main screen and can be observed and operated at any time
1	Mode selection	 AUTO, Switch to automatic mode MDI, Switch to MDI mode, the MDI input pop-up window w pop up, and the screen will switch to F4 processing monito JOG, Switch to continuous inching mode INJOG, Switch to incremental jogging mode MPG, Switch to handwheel mode HOME, Switch to origin search mode
2	Handwheel simulation	 After clicking, press the upper left corner of the keyboard and the box will turn green, and you will enter the handwheel simulation mode Click again to cancel
	Single section execution	 After clicking, the box in the upper left corner of the button will turn green, and the single block execution mode will be entered Click again to cancel

4	Reset	Trigger reset action
5	Main interface	 After clicking, switch directly to the main interface manual panel Axial movement buttons, peripheral control buttons and other value-added functions can be placed here
6	Magnification adjustment	 G00 magnification adjustment, 0%, 25%, 50%, 100% G01 magnification adjustment, 0%, 10%, 20%, 150% Spindle speed magnification adjustment, 0%, 10%, 20%, 120%
7	Processing information	 Date Time Login username Workpiece coordinate system, G54, G55 Current execution program name Current execution line number

Main interface/manual panel



*\$\$ta*ΓProMax | 20

6.2. Boot interface



Press F1 to turn off the alarm. In HOME mode, click Cycle Start. Each axis of the machine will automatically return to the mechanical origin, and the machine tool will immediately start the zero return operation. After the zero return is completed, the pro cessing operation can be carried out.

* Every time you turn on the machine, you must confirm that there are no obstructions around the machine, follow the above operations to return to the origin, and wait for each axis of the machine to return to the mechanical origin, otherwise the limiter wil I be ineffective. If it does not return to the origin, the machine will continue to move beyond the maximum stroke, causing safety accidents such as tool breakage or bed damage.

C54 C01 184		C00	307 NO L1	Coord.	2024/1/30 SPD 102%	15:20:42	DEFAUL
Normai Viode		000				p-	8.33
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6.3. F1 operator panel

Path: F1 Operator Panel

Explanation

- The operations required by the operator for production are concentrated in F1
- During processing, all processing operations can be completed only in F1
 - Select a work order
 - Execute processing
 - Adjust the processing sequence and work station
 - Operator login and logout
 - Working List form
 - Graphical simulation viewing
- Among them, the preset station 1 is G54, and the station 2 is G55.
- The processing status is preset as unprocessed, open, and processed.

The information displayed in the Working List is

Sequence number	NC file name	Station	Processing status
1	00001.nc	1	Unprocessed
2	00002.nc	2	Unprocessed

6.3.1. Processing panels

(554		-	NcTemp	0/G0307 N	10 L1	Cool	rd.	2024	1/1/30	15:20:42	DEFAULT
GØ	1 100%	G1-	61+	G00	100%	s	0- 00	F SPD)	100%	Sp- Sp+	0.000
Nc	rma Mode					G 90	Ma	chine	Abs	solute	Dist. To Go	AUTO
						G 40	X	0.000	X Y 1	-10.000	X 0.000 Y 0.000	MDI
						G 1	X Y Z	1824.750 0.000	Z	-10.000 814.750 10.000	Y 0.000 Z 0.000	JOG
						M 0					1	-
									Total	0		Inc J0
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No.	Worki	ngList	Reg	State Undone				TotalWorl	Time	1480 Se	c	S.B.K
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<<	F1 Process	E2 Exchang	e Row F3 File	Manage	F4 Reset	List		F6 C	lear List	F7 Logir	1 40.000	>>9
	Frame	The Excitating	10110			AUTOS III						And the second second

Path:

F1 operator panel - F1 processing panel.

File page button: perform page up and down operations on the file list.

Station: Display single station/double station status.

Processing status status: The processing status of the corresponding plate is displayed.

Click the drop down button to modify the processing status of the plate. (Unprocessed, whole material, labeling, pushing material, processing Current processing quantity quantity: Displays the total number of files processed and which file is currently being processed.

Processing graphics preview preview: Display the graphic simulation corresponding to the current processing file.

6.3.2. Move bank number

			_			_	1307 N			oord.		2024/1/3		15:21:0	-	DEFAUL
GØ	1	100%	G1-	1+	G00		100%			<u>0</u> 0+	SPD	100	The second se	Sp- Si	+	0.00
10.00	irmai Mode				1.1			G 90		Machine	\$	Absolute		Dist. To	Go	AUTO
								G 40	Х	0.	000	X -10.	000	ç	0.000	MDI
								G 1	XYZ	0. 1824. 0.	750 000	X -10. Y 1814. Z 10.	000) 750) 000 2		0.000	JOG
-								M 0						19		
122						9	,					Total 0				Inc J
																MPG
											Cuttin	g the 0				HOME
								Ormali		rate 1000	000	RealFeed		0	nm/min	T
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	-	STREET,														

Path: F1 Operator Panel→F2 Move Line Number.

Description: Used to adjust the order of the list after the list is generated.

Move up

Path : F1 Operator Panel+F2 Move Line Number+F1 Move Up)

Description: Used to move a single NC program up after the list is generated and process it in advance.

Operation method

- ① Click to select the processing program that needs to be moved.
- 2 Click the function key to move the program.
- ③ You can click multiple times to move continuously.

Move Downward

Path: F1 Operator Panel+F2 Move Line Number+F1 Move Up

Description: Used to move a single NC program downward after the list is generated to postpone processing.

Operation method

- ① Select the processing program that needs to be moved.
- 2 Function key mover.
- 3 Click multiple times to move continuously.

6.3.3. Work order selection

654				NcTemp	1 G0307 NO 1	1	Coord.	202	4/1/30	15:21:19	DEFAULT
G01	100%	61-	51+	G00	100%	G0-	GØ+	SPD	100%	Sp- Sp+	0.000
DiskAlopenCNC	WcFiles Fr	ee Space 391:	3244KB								AUTO
Name AutoLabel		Modified	and the second second	Comme	ent						MDI
											JOG
DIBlock		2024/01/29 1 2012/03/20 1	14:48:22								Inc J00
B TEST_SP		2017/03/29 1 2024/01/28									MPG
12		2024/01/28 2024/01/29									HOME
15	nc	2024/01/29									T I
											MPG SIM
											5.B.K
											Main
											Set Too
											Set Dril
			e Rea	4	dag -		Cyc	le Start	Feed Hold	Reset	Alarm
<< F1 Ou	tput List	F2 SelectAll	F3 Car	ncelAll	F4 Delete Files	F5 Add	Working		F7 Chang USB/Loca		ort Files >>

Path: F1 operator panel → F3 work order selection.

Description: Used to generate processing lists and import files.

Fl output work list

Path: F1 operator panel \rightarrow F3 work order selection \rightarrow F1 output work list.

Description: After selecting the processing program, generate a work list.

Operation method

- Select the required processing program (you can directly click the folder) or select the xml list file.
- Click the output worklist function key.

Select all F2 files

Path: F1 operator panel \rightarrow F3 work order selection \rightarrow F2 file selection all.

Note: When selecting files, you can select all files at once.

Operation method

Click the File Select All function key and all programs and labels will be function key and all programs and labels will be selected (excluding folders)selected (excluding folders).

F3 deselects all

Path: F1 operator panel \rightarrow F3 work order selection \rightarrow F3 deselect all.

Note: When selecting files, you can deselect all.

Operation method

Click the Cancel Select All function key to cancel all selected programs and labels.

F4 deletes selected files

Path: F1 operator panel \rightarrow F3 work order selection \rightarrow F4 delete selected F1 operator panel \rightarrow F3 work order selection \rightarrow F4 delete selected file.

Note: After selecting files, you can delete the selected files.

Operation method

① Select files to deleteSelect files to delete.

② Click the delete selected file function key, and all selected files will be Click the delete selected file function key, and all selected files will be deleted.

F5 appends work list

Path: F1 operator panel \rightarrow F3 work order selection \rightarrow F5 append work list F1 operator panel \rightarrow F3 work order selection \rightarrow F5 append work list.

Note: You can continue to add content to the existing work list.

Operation method

1) Select files to addSelect files to add.

② Click the append work list function button, and the selected files will be Click the append work list function button, and the selected files will be appended to the original list.

F7 Switch (USB/System)

Path: F1 operator panel \rightarrow F3 work order selection \rightarrow F7 switching device F1 operator panel \rightarrow F3 work order selection \rightarrow F7 switching device (USB/system).

Description: This button can switch the file management screen between System and USB.

F8 import file

Path: F1 operator : F1 operator panel \rightarrow F3 work order selection \rightarrow F8 import filepanel \rightarrow F3 work order selection \rightarrow F8 import file.

Description: This button can import files from USB into the system.

6.3.4. Satus reset

Path: F1 operator panel -> F4 status reset.

Note: The processing status of all files has changed to "Unprocessed".

6.3.5. Bakpoint regression

Path: F1 operator panel \rightarrow F5 breakpoint returnF1 operator panel \rightarrow F5 breakpoint return Explanation:

- Processing is interrupted. You can click this button to continue the Processing is interrupted. You can click this button to continue the processing program.
- Be careful not to click breakpoint regression multiple times Be careful not to click breakpoint regression multiple times continuously, otherwise the status bar will be blank.

Operation method

① Click the breakpoint return function key, a popClick the breakpoint return function key, a pop--up window will pop up, up window will pop up, click OK.

⁽²⁾ After the system enters the After the system enters the processing monitoring screen, confirm the processing monitoring screen, confirm the breakpoint position, enter the breakpoint, and start processing.breakpoint position, enter the breakpoint, and start processing.

③ After processing is completed, return to the work list screen and continue After processing is completed, return to the work list screen and continue subsequent processing.

6.3.6. Clear the list

Path: F1 operator panel -> F6 clear listF1 operator panel -> F6 clear list.

Description: Clear all the lists.

6.4. F2 program editor

654	NcTemp	G0307 NO L1	Program		2024/1/30	15:22:52	DEFAULT
G01 100% G1- G	.+ G00	100%	C0	SPD	100%	So	0.000
EditProgName : no Line 1	Column						AUTO
G54G9D		ACCU A DESIGN	-	-	A 100		MDI
						,	
							JOG
600 X30.001 Y30.000 Z30.000						/	Inc J0
600 X30.001 Y30.000 Z15.000							MPG
G01 X30.001 Y30.000 Z-5.000							
G00 X30.001 Y30.000 Z30.000						14	HOME
G00 X60.001 Y30.000 Z30.000							T 1 M 0
GOD X60.001 Y30.000 Z15.000							MPG ST
G01 X60.001 Y30.000 Z-5.000					State of the local division of the local div	11	
G00 X60.001 Y30.000 Z30.000 G00 X120.001 Y60.000 Z30.000							S.B.K
G00 X120.001 Y60.000 Z15.000							Main
G01 X120.001 Y60.000 Z-5.000							Set Too
G00 X120.001 Y60.000 Z30.000							Set Dri
G00 X60.001 Y120.000 Z30.000							•
					-	•	-
					Feed Hold	Reset	Alarm
	1						
< F1 Execute F2 Delete Line	F3 CanCycle		F5 SubEdit Menu	F6 Teach	F7 Simul	ation F8 File M	anager
		4	-		and the second second		

Path: F2 program editor

Note: The control system provides program editing function, and program editing actions can be performed under this function key.

Instructions

① Use the direction keys $[\uparrow] [\downarrow] [\downarrow] [\downarrow]$ to move the cursor.

② Use [Page Up] [Page Down] to switch between the previous and next

pages.

③ Use [Home] [End] to quickly switch to the front or back of the line

where the cursor is located.

④ Use the shortcut key [Prog File] to quickly switch between the 『Program Editing』 『File Management』 pages.

6.4.1. Load and execute processing

Path: F2 program editing \rightarrow F1 load program processingF2 program editing \rightarrow F1 load program processing.

Description: This button can designate the program being edited as a processing program and switch the screen to the "Processing page".

* Note that this button is invalid during processing.

6.4.2. Delete row

Path: F2 Program Edit → F2 Delete Line.

Description: Delete the row where the cursor is currently located.

6.4.3. Graphical auxiliary input

Path: F2 Program Edit → F3 Graphic Auxiliary Input.

Note: When compiling the program, because the system provides many G codes, and the argument definitions of different G codes are also different, a graphic auxiliary input function is provided to illustrate with pictures, so that the G codes can be easily edited.

Insert loop

Path: F2 Program Edit → F3 Graphic Auxiliary Input → F1 Insert Loop.

Instructions

① In the current editing program, move the cursor to the place where you want to add a loop, click "Insert Loop", and follow the instructions of the graphical auxiliary input to select the loop to be inserted and set the required arguments.

② After editing is completed, press "OK", and the edited loop will be added to the next line where the cursor of the program is being edited.

Edit loop

Path: F2 program editing \rightarrow F3 graphics auxiliary input \rightarrow F2 editing loop.

Description: Edit the loop where the current cursor is located.cursor is located.

Operation instructions: Move the cursor to the modified loop and press "Edit Loop". The loop content at the cursor position of the program currently being edited will be substituted into the graphical auxiliary input screen. You can reedit the loop and th en press "Confirm" to modify the loop.

6.4.4. File management

G54		NcTem	G0307 NO L1	File Manag	er 20.	24/1/30	15:24:40	DEFAULT
	0% <u>G1-</u> G1+	G00	100%	G0- G0+	SPD	100%	Sp- Sp+	0.000
)iskAl0penCNCINcFiles	Free Space: 3913244		and the second second					AUTO
lame	Modified	Comm	ent					MDT
AutoLabel								
NoTemp MDIBlock	2024/01/29 11:18:		0.Y0.Z0.					JOG
00001	2012/03/20 14 48		9 L100;					Inc J0
TEST_SP	2017/03/29 10:03: 2024/01/28 18 57		00.Y100.Z100.C100					MPG
	2024/01/28 18:57						16	HOME
	2024/01/29 10:36:		90				14	HUME
10	2024/01/29 10:06:	48						0 0
						100		MPG SI
								S.B.K
						100		
								Main
								Set Too
								Set Dril
		Ready	394		Cycle Stort	Feed Hold	Reset	Alarm
< F1 New File	F2 Copy File	F3 Delete File	F4 File Transfer	F5 Execute	F6 Select DN			100
FTINEWFILE	F2 Copy File	F3 Delete File	F4 File Transfer	P5 Execute	File	Manager	a mil and a sur and	

Path: F2 program editing -> F8 file management.

Explanation:

- This button can perform file management functions on all processing files in the specified drive letter of the system installation configuration.
- The system processes the main program and its subfolders marked by an arrow icon.

The sorting method can be set through the **[File List Sorting Method]** in the HMI parameter setting screen.

When entering this screen, all files may not have been added to the list. The screen will flash during the adding process but it will not affect the operation. The **Select All** button will not be enabled until all files are added.

Instructions

(1) Use the direction keys[\uparrow][\downarrow] to move the to move the cursor.

② Use [Page Up] [Page Down] to switch between the previous and next to switch between the previous and next pages.

③ Press the [ENTER]key, and the file designated by the cursor will be designated as the edit file. The program content of the file will be displayed on the screen, and editing actions can be performed.

Open new document (file)

Path: F2 program editing → F8 file management → F1 open new file.

Description: This button can add a file. The newly added file will be designated as the file currently being edited.

Instructions

Click **Open New File**, and a dialog window will pop up. Enter the file name of the new file.

* Notice:

① The default file format is without an extension. If you want to create a file with an extension, such as *.NC, just enter *.NC when setting the file name.

③ The length of the file name (including file extension) cannot exceed 31 characters.

Copy files (archives)

Path: F2 program editing \rightarrow F8 file management \rightarrow F2 copy file.

Description: This button can copy the file currently selected by the cursor.

Instructions

① Use the arrow keys $[\uparrow]$ $[\downarrow]$ to select the file you want to copy.

② After selecting, click **Copy File**.

③ In the pop up dialog window, enter the file name of the new file.

* Notice:

① The default file format is without an extension. If you want to create a file with an extension, such as *.NC, just enter *.NC when setting the file name.

2 The length of the file name (including file extension) cannot exceed 31 characters.

Delete Files

Path: F2 program editing \rightarrow F8 file management \rightarrow F3 delete files.

Description: This button can delete the file currently selected by the cursor.

Instructions After clicking **Delete File** a file selection box will appear in front of all files on the **File Management** page. Use the arrow keys [\uparrow] [\downarrow] to select the file you want to delete.

Sub-function key description

- Select: Mark the files to be deleted. You can mark multiple files at the same time or cancel the marked files.
- Select all: mark all files.
- Deselect: Deselect all flagged files.
- Delete files: delete all marked files.
- Delete all files: Delete all files in the disk volume.
- * Note: Files currently being processed and files currently being edited cannot be deleted.

File transfer

Path: F2 program editing → F8 file management → F4 file transfer.

Description: Perform file exchange between the controller and external folders.

File (file) input

Path: F2 program editing > F8 file management > F4 file transfer > F1 file input.

Description: Input external folders or files into the controller.

Screen description

Above is the external disk option, you can choose the following options.

- USBDisk.
- DiskA.
- Network.
- USBDisk2.

The lower left corner shows the file structure of the external disk volume.

The lower right corner shows the processing files currently stored on the internal disk of the controller.

Sub-function key description

- Copy: Import marked files and folders from external disk to internal disk.
- Selection: Press this button to mark files. You can mark multiple files at the same time, or you can cancel marked files.
- Select all: mark all files.
- Deselect: Deselect all flagged files.
- Change disk drive: external disk can be changed.

Instructions

(1) After clicking [File Import] a file selection window will pop up.

2 Default external disk is USB Disk.

③ To change the file output address, click 「**Change Disk Drive**」, switch the cursor to the external disk option, move to the external disk where the file is to be output, and type [Enter], to change the left block to the file of the external disk.

4 Press [Switch focus to input and output], to switch the focus from the external disk to the internal disk, and vice versa.

(5) If you want to switch to the external disk folder, use the direction keys $[\uparrow] [\downarrow]$, move to the target folder, and type [Enter].

- 6 Use the direction keys $[\uparrow] [\downarrow]$ to select the file to be output in the internal disk.
- O Move to the file to be exported, press [Select] or type [Space], to mark the file.
- (8) After marking all files to be imported, click [Copy], and all marked files

and folders will be output from the internal disk to the external disk.

* Please note that all files in the folder will be copied.

Load and execute processing

Path: F2 program editing \rightarrow F4 file management \rightarrow F5 loading and execution processing Description: This button can designate the file where the current cursor is located as the current processing file, and at the same time switch the screen to the **"Processing Monitoring"** screen.

Instructions

① Use the direction keys [↑] [↓] to select the file. After selecting, press the **Load and Execute Processing** button, and the selected file will be designated as the processing file.

2 The screen switches to the $\llbracket \textbf{Processing Monitoring} \rrbracket$ page.

* Note: This button is invalid during processing.

G54		NO STERIOS	NcTemp	\G0307 NO L1	07 NO L1 Coord.		2024/1/30	15:26:15	DEFAUL
GØ1	100%	G1- G1+	600	100%	60- 604	SPD	100%	Sp- Sp+	0.00
External Shift		G54P1(G54)		G54P2(G55)			Machine		AUTO
х	10.000	x	0.000	x	0.000		X Y	0.000 1824.750	IDM
Ŷ	10.000		0.000	Y	0.000		Z	0.000	JOG
z	-10.000	Y Z	0.000	Z	0.000				Inc J
							Deletion	16270	MPG
							Relative	0.000	НОМ
							X	0.000 1824.750	T
G54P3(G56)		G54P4(G57)		G54P5(G58)			Y Z	0.000	M I I
x	0.000	x	0.000	x	0.000				
Ŷ	0.000	Ŷ	0.000	Y	0.000		Aux. Coord.		S.B.
z	0.000	Z	0.000	Z	0.000		X	0.000	Mai
							Y	0.000	Set T
							Z	0.000	Set Dr
			wady	305		Cycle Sto	Feed Hol	d Reset	Alar
F1 V Coor	VorkPiece F2 To		Tool Tip easure	F4 Apply Mach	F5 Apply Rel	F6 Zero Coord	Rel. F7 Zero Coord	All Rel F8 Inc. In	out 1
	4	IVI8	sasul e	1 Coord	Colord	Coord	Coold		

6.5. F3 offset/setting

Path: F3 Offset/Set

Explanation:

- Create a group under this function to perform offset function settings and function settings.
- You can use the shortcut key [Offset/Setting] to quickly switch pages in this group.

G54	100%		NcTemp\G03		Coord.	2024/1/30	15:27:38	DEFAL
GØ1	100%		G00	100% 0		PD 100%	Sp- Sp+	0.1
External Shift		G54P1(G54)		G54P2(G55)		Machine		
х	10.000	X	0.000	X	0.000	X Y	0.000 1824.750	М
Y	10.000	Y	0.000	Y	0.000	Z	0.000	J
z	-10.000	z	0.000	z	0.000			Inc
						Relative		М
						X	0.000	H
						Ŷ	1824.750	T
G54P3(G56)		G54P4(G57)		G54P5(G58)		Z	0.000	MPG
x	0.000	х	0.000	х	0.000			S.
Y	0.000	Y	0.000	Y	0.000	Aux. Coord.		
Z	0.000	z	0.000 -	Z	0.000	X	0.000	_
						Y	0.000	Set
						Z	0.000	Set I
						e Stort Reed Hold	Reset	Ald
						Apply Mach.		and second

6.5.1. Workpiece coordinate system

Path: F3 Offset/Setting → F1 Workpiece Coordinate System

Explanation:

This function key can switch to the "Workpiece Coordinate System" page to set the workpiece coordinate system.

If there is no G54~G59.10 set in the NC program, the system defaults to G54.

External coordinate offset: coordinate system that acts on all coordinate systems (G54~G59.10).

Instructions

① Use the direction keys $[\uparrow] [\downarrow] [\downarrow] [\downarrow]$ to move the cursor.

② Use [PageUp] [PageDown] to switch between the previous and next pages.

* Note: After setting the coordinate system of the finished workpiece, you need to set the tool length compensation again.

Modification time

External bias:

- Modifiable: ready or not ready.
- Cannot be modified: Processing and reconciliation.

Workpiece coordinate system (G54P1 (G54), G54P2 (G55), ..., G54P100).

- Modifiable: ready or not ready.
- Cannot be modified: during processing and unprocessing, and must be modified to the workpiece coordinate system in use.
- * When it cannot be modified, a warning window will pop up.

Mechanical coordinate teaching

Path: F3 Offset/Setting → F1 Workpiece Coordinate System → F1

Mechanical Coordinate Teaching

Description: Set the workpiece coordinate coefficient value where the cursor is currently located to the current corresponding mechanical coordinate value.

Instructions

- 1) Move the machine to the target location.
- 2 Move the cursor to the workpiece coordinate system to be modified.
- ③ Click 「Mechanical Coordinate Teaching」.
- ④ The workpiece coordinate coefficient value where the cursor is located will be changed to the corresponding mechanical coordinate value.

Operation example

- ① The current X axis mechanical coordinate is 5.000.
- 2 The current X axis coordinate of G54 is 0.000.
- ③ Move the cursor to the X axis coordinate of G54.
- (4) Click [Mechanical Coordinate Teaching].
- (5) The X axis coordinate of G54 is changed to 5.000.

Relative coordinates teaching

Path: F3 Offset/Setting > F1 Workpiece Coordinate System > F2 Relative

Coordinate Teaching

Description: Set the coordinate coefficient value of the workpiece where the current cursor is located to the corresponding current relative coordinate value.

Instructions

- ① Move the machine to the target location.
- 2 Move the machine to the target location.
- 3 Click [Relative Coordinates Tutorial].

④ The workpiece coordinate coefficient value where the cursor is located will be changed to the current corresponding relative coordinate value.

Operation example

- ① The current X axis relative coordinate is 5.000.
- 2 The current X axis coordinate of G54 is 0.000.
- ③ Move the cursor to the X axis coordinate of G54.
- (4) Click [Relative Coordinates Tutorial]
- (5) The X axis coordinate of G54 is changed to 5.000.

Auxiliary coordinate teaching

Path: F3 Offset/Setting -> F1 Workpiece Coordinate System -> F3 Auxiliary

Coordinate Teaching

Explanation:

Set the workpiece coordinate coefficient value where the current cursor is located to the corresponding current auxiliary point coordinate value.

The coordinate value of the auxiliary point will only have a numerical value after using the centering function.

Instructions

① Use the centering function to calculate the numerical value of the auxiliary

point coordinates.

2 Move the cursor to the workpiece coordinate system to be modified.

③ Click 「Auxiliary Coordinate Teaching」.

④ The workpiece coordinate coefficient value where the cursor is located will be changed to the corresponding auxiliary point coordinate value.

Operation example

① The coordinate of the front X axis auxiliary point is 5.000.

- 2 The current X axis coordinate of G54 is 0.000.
- ③ Move the cursor to the X axis coordinate of G54.
- ④ Click 「Auxiliary Coordinate Teaching」.
- (5) The X axis coordinate of G54 is changed to 5.000.

Incremental input

Path: F3 Offset/Setting→F1 Workpiece Coordinate System→F4 Incremental Input

Description: Change the workpiece coordinate coefficient value where thecursor is currently located to (the value where the cursor is located + the enter ed teaching value)

Instructions

- ① Move the cursor to the workpiece coordinate system to be modified.
- 2 Enter the value to be taught.
- ③ Click 「Increment input」.

④ The workpiece coordinate coefficient value where the cursor is located will be changed to the value where the cursor is + the value input by the teaching.

Operation example

- The current X axis coordinate of G54 is 5.000.
- Move the cursor to the X axis coordinate of G54.

- Enter 10.000
- Click [Increment input]
- The X axis coordinate of G54 is changed to 15.000

Mechanical incremental teaching

Path: F3 Offset/Setting → F1 Workpiece Coordinate System → F6 Mechanical Incremental Teaching

Description: Change the workpiece coordinate coefficient value where the

cursor is currently located to (the current corresponding mechanical

coordinate value + the entered teaching value)

Instructions

- ① Move the cursor to the workpiece coordinate system to be modified
- 2 Enter the value to be taught.
- 3 Click [Mechanical Incremental Teaching]

④ The workpiece coordinate coefficient value where the cursor is located will be changed to the current corresponding mechanical coordinate value + the value input by the teaching

Operation example

- ① The current X axis mechanical coordinate is 5.000
- 2 Move the cursor to the X axis coordinate of G54
- 3 Enter 10.000
- (4) Click [Mechanical Incremental Teaching]
- (5) Change the X axis coordinate of G54 to 15.000

6.5.2. Tool settings

	G54 G01 1	00% G	- G1+	G00	100%	CO-	C/ Setti	spd 2	100%	15:29:00	DEFAULT 0.000
	Vicde(A)bsolute (I		Massire		1000			510	Machine		AUTO
Juc	Absolute		1							0.000	MDI
	Diamete		Length	(H)					XYZ	0.000 1824.750 0.000	JOG
	Geometry	Wear	Geometry	Wear	-			_			Inc J0G
	0.000	0.000	-250.052	0.000							MPG
	0.000	0.000	0.000	0.000					Absolute	10.000	HOME
	0.000	0.000	0.000	0.000					X Y Z	-10.000 1814.750 10.000	T 1
	0.000	0.000	0.000	0.000					-	10.000	M Ø MPG SIM
	0.000	0.000	0.000	0.000							5.B.K
	0.000	0.000	0.000	0.000					Relative		Main
			0.000	0.000					X Y Z	0.000 1824.750	Set Tool
	0.000	0.000							z	0.000	Set Dril
3	0.000	0.000	0.000	0.000							
				ay J	- 90			icte Star	Feed Hal	Reset	Alarm
<<	F1 Clear Z C	Coord. F2 Set Mach		Tool Rel					F7 Tool	No	
			addalaad all all and a dadadad		The second second	and the states					

Path : F3 Offset/Setting→F2 Tool Setting

Explanation

- This function key can switch to the correction setting and perform various correction settings.
- (Tool tip + tool radius wear compensation) is the actual G41/G42 compensation amount.
- (Tool length compensation + tool length wear compensation) is the actual G43/G44 compensation amount.

Parameter Description

- Radius: G41/G42 tool radius Dn compensation (not diameter).
- Radius wear: Small tool radius adjustment.
- Tool length: G43/G44 tool length Hn compensation.
- Tool length wear: small size adjustment of tool length.

Instructions

- ① Use the direction keys $\uparrow \ \downarrow \ \leftarrow \ \to \$ to move the cursor.
- ② Use [PageUp] [PageDown] to switch between the previous and next pages.

③ Input.

- Generally use the absolute input type to input tool tip or tool length compensation.
- Generally use incremental input form to input tool radius wear compensation or tool length wear compensation.

④ A bsolute input

- Type [A] and press [ENTER]
- The value where the cursor is located will be set as [input value].

(5) Incremental input

- Type [I] and press [ENTER]
- The value where the cursor is located will be set as *[input value]+[current value]* where the cursor is located.

6 Measurement input

- Type [Z]and press [ENTER], the tool length compensation of the line where the cursor is located will be set to the current Z axis [relative coordinate] value.
- Press F2 to input mechanical coordinates. The tool length compensation of the row where the cursor is located will be set to the current Z axis [mechanical coordinate] value.
- Press F2 for relative coordinate input. The tool length compensation of the line where the cursor is located will be set to the current Z axis ["relative coordinate] value.

Clear Z axis relative coordinates

Path: F3 Offset/Setting→F2 Tool Setting→F1 Clear Z axis relative coordinates

Description: Clear the current Z axis value in relative coordinates

Knife number information

• Path: F3 Offset/Setting \rightarrow F2 Tool Setting \rightarrow F7 Tool Number Data

Tool life management

• Path: F3 Offset/Setting→F2 Correction Setting→F8 Tool Life Management

654			NcTemp\(0307 NO L1	Coord.		2024/1/30	15:40:24	DEFAULT
601	100%	G1- G	1+ G00	100%	C0- C0+	SPD	100%	So- So+	0.000
Single tool	3 Single workpi Multi-workpieco ulti-workpieco	ce	Tool No. T Feedrate F Use Reference Ref Coord. X Ref Coord. X Ref Coord. Z Min. Z Mach. H Safe Z After Mea Select if use Ref 1:Set All measur 2:If not use Ref, to upper of mea 3:Press F1, Meat WorkPiece No.	Point e parameter Take tool tip isurement	1 400 1 207.200 3217.000 -170.000 -270.000 0.000		Machine X Y Z Relative X Y Z Aux. Coord.	0.000 1824.750 0.000 0.000 1824.750 0.000	AUTO MDI JOG Inc J0 MPG HOME MOME S.B.K Main
~3)			Do tool tip measu 1.Take tool tip to 2:Press F3, Delta Gauge Air Blow:	top of good a Z Set	elta Z 0 OFF: M	0 Cycle St	X Y Z	0.000 0.000 0.000 Reset	Set Toc Set Dri Alarm

6.5.3. Automatic tool setting

Path: F3 Offset/Setting→F3 Automatic Tool Calibration

Explanation:

- The machine is equipped with a tool setter. By setting relevant parameters, the machine can be controlled to move to the position of the tool setter for automatic tool measurement.
- According to different situations, it is divided into the following measurement methods:
 - Single tool, single workpiece
 - Single tool for multiple workpieces
 - Multiple tools and multiple workpieces

6.5.4. Relative coordinate clear

Path: F3 Offset/Setting→F6 Relative Coordinate Clear

Description: Return the value of relative coordinates to zero.

Operation method: After entering the axis to be calculated, click this button

Operation examples

- ① The X axis relative coordinate value is 10.000
- 2 After typing [X], click [Clear Relative Coordinates]
- ③ Then the X axis relative coordinate value will be changed to 0.000

6.5.5. Clear relative coordinates

Path: F3 Offset/Setting→F7 Clear all relative coordinates

Description: Return the values of all relative coordinates to zero

Operation example

1 The current relative coordinate value of the X axis is 10.000 and the relative coordinate value of the Y axis is 5.0000

2 Click [Clear all relative coordinates]

③ Then the X axis relative coordinate value will be changed to 0.000, and the Y axis relative coordinate value will be changed to 0.000.



6.6. F4 processing monitoring

Path: F4 processing monitoring

Note: This function creates a group to provide the necessary information for monitoring during processing.

Function key description

F1: LoaderEdit

Description: Load the current processing file into the program editor for editing, and switch the screen to [®]Program Edit [®]

F2: Graphical simulation display

Description: Display graphic analog components

F3: MDI input

Description: In MDI mode, edit the program executed by MDI (open this mode on the right side of the main screen).

F4: Processing information settings

Description: Switch the display between related [[]Processing Information] and

「Processing Settings」.



Switch screen one: breakpoints, processing parameters, number of workpieces



Switch screen two: G code status, time, magnification

Loadi	ng Rate		Speed	Override	Loading	
	4		24000 RPM	100 %		%
-	3		O RPM	100 %		0 %
	50	[%] S3	O RPM	100 %		0 %
			0 RPM	100 %		0 %
S		S5	0 RPM	100 %		0 %
	24000 RF	™ S6	O RPM	100 %		0 %

Switch screen three: spindle speed, magnification, load rate

6.6.1. S creen description

Machine monitoring area

This area will display the current machine information.

- Absolute coordinates
- Processing remaining distance.
- Feed speed.
- Spindle speed.

Program code monitoring area

- This area will display the programs currently being processed.
- The yellow light bar will indicate the current block of program execution.

Processing information display area

Explanation:



- This area overlaps with the [Processing Setting Area].
- Use 「Processing Information/Settings」to switch the display.

Screen description

1) G code status

Display the G code currently executing in the system.

2 Processing time

- The single processing time of the current workpiece.
- The calculation will be reset when the program starts.
- ③ Accumulated processing
- Current total processing time.

(4) Magnification

- G00 magnification.
- G01 magnification.
- Spindle magnification.

⑤ Total number of processes

- Total workpieces processed by the machine.
- The system will not automatically perform any zeroing action.
- When manually returning to zero, please press [Processing Information/Settings], switch to [Processing Settings Display], and set [Total Number of Workpieces] to 0.

6 Number of workpieces

- Every time processing is executed, calculation will start from zero.
- Display the number of workpieces currently processed.

⑦ Starting block

• The starting block of processing can be set.

Instructions

- n: Specify the starting section as the nth line.
- L + n: Specify the starting section as the nth line.
- N + n: Search for the line number where N+n is located and specify this line as the

- T+n: Search for the line number where T+n is located and specify this line as the starting line.
- If the specified line number exceeds the maximum number of lines in the program, specify the last line of the program.
- Return method of the starting section.

⁽⁸⁾ Processing tool information

- T
- 4 code display.
- The first 2 digits are the tool number currently being executed.
- The last two digits are the correction number of the tool currently being executed.

Processing setting display area

Explanation

- This area overlaps with the [Processing Information Area].
- Use 「Processing Information/Settings 」to switch the display.

Screen description

1) Interruption point serial number

- Displays the sequence number (N) of the last program interruption.
- 2 Break point line number
- Displays the line number (L) where the program was last interrupted.

3 Spindle speed

- Set the spindle speed.
- Can be set during processing and responds immediately.

④ Feed speed

- Set the feed speed.
- Can be set during processing.
- It will be changed after all the sections you want to solve are executed.

(5) Total number of workpieces

- Set the total number of pieces processed by the machine.
- The system cannot be reset to zero automatically and can only be reset to zero manually.

6 Number of workpieces

- Set the current number of pieces processed by the machine.
- When changing the processing file, the workpiece counter will be reset to zero.
- When the set M code is executed (parameter 3804 can specify the M code), the workpiece counter will automatically increase by one, and the single piece processing time will be reset to zero. When the required number of workpieces is reached, it will automatically enter the pause state.

$\ensuremath{\overline{\textit{O}}}$ Number of required workpieces

- Set the upper limit of the number of processed pieces.
- When the number of workpieces reaches the number set by the required number of workpieces, an alarm window will pop up and processing will be suspended.

Graphic analogy area

Explanation

- This area can display the tool movement trajectory of the current processing file.
- Use [Graphic Analog Display Switching] to switch the display.

6.6.2. Load program editor

Path: F4 processing monitoring \rightarrow F1 loading program editing.

Description: Load the current processing file into the program editor for editing, and switch the screen to **"Program Edit"**.

* Note: This button can be executed during processing, and the screen will switch to "Program Editing", but the current processing file cannot be edited.

6.6.3. Graphical simulation display

Path: F4 processing monitoring \rightarrow F2 graphic analog display.

Explanation:

- Select whether to display the graphic analogy function.
- The [Graphic Adjustment] function can only be performed in the [Graphic Analog Display] state.

6.6.4. MDI input

Path: F4 processing monitoring→F3 MDI input.

Description: Edit the program executed by MDI.

Instructions

1 Switch mode to $\llbracket \text{MDI} \rrbracket.$

② After clicking 「MDI Input」 the editing window will pop up.

③ After editing the MDI program, press <code>「OK]</code>, and the edited program will be stored in the MDI Block.

④ In the 『MDI 』mode, execute Cycle Start to process the program edited by MDI.

* Note that this button is only valid in "MDI" mode

6.6.5. Processing information/settings

Path: F4 processing monitoring \rightarrow F4 processing information/settings.

Description: Switch the display between.

「Processing Information Area」and 「Processing Settings」.

6.6.6. Wear setting

Path: F4 processing monitoring \rightarrow F5 wear setting.

Explanation

- Set tool wear.
- Actual tool length = tool length + tool wear.

Parameter Description

Wear: Small size adjustment of tool length.

*Note that after setting the tool length, the corresponding wear will be reset to zero.

6.6.7. Processing record form

Path: F4 processing monitoring→F7 processing record form **Display screen**

654			IcTemp\G0307 N0 L1	Monitor 20	24/1/30 15:35:21	DEFAUL
GØ1	100%	G1- <u>G1+</u> C	00 100%	CO- EO+ SPD	100% Sp- Sp+	0.00
File Name		A®A®×e^E^O'Ƶ.nc		File Comment		AUTO
Require Part	1000	0		Start DateTime	1/30/2024 3:09 PM	MDI
Part Count		0			0	JOG
Cycle Time		00:00:00			0:00:00	Inc JO
No.	User	Program	Start DateTime	Total Time Total Part C	Comment	MPG
						HOME
						T 1 M 0
						MPG SI
						5.B.K
						Main
						Set Too
						Set Dri
					Feed Hold Reset	Alarm
			29 0	Contraction of the start		A CONTRACTOR OF CONTRACTOR
	ve Work	F2 Clear Work				

This form can view the current processing records and export the processing records to an external disk. It can record up to 500 sets of execution processing files.

Table record content:

Serial number, user (authority management), program name, start time and date, total processing time, number of output workpieces, program comments.

6.6.8. Clear accumulated time

Path: F4 processing monitoring \rightarrow F8 clear accumulated time.

Description: Return the accumulated processing time to zero.

6.7. F5 maintenance

Path: F5 Maintenance

Description: This function page can display system alarms, network settings, quick diagnosis, PLC parameter byte settings and software version information

6.7.1. Alarm display

Path: F5 Maintenance→F1 Alarm Display

Description: This function page can display system alarms.

Existing alerts

Path: F5 Maintenance→F1 Alarm Display→F1 Existing Alarm

Description: Display the alarm content currently occurring in the system

Historical Alerts

Path: F5 maintenance \rightarrow F1 alarm display \rightarrow F2 historical alarm

Description: Display the alarm content that has occurred in the system in the past

*Note that not all alerts will appear in historical alerts, for example: MACRO alerts

Save alert

Path: F5 maintenance→F1 alarm display→F3 storage alarm

- Save all alarms in the currently displayed alarm page to an external disk
- For example, if the current page stays at [[]Existing Alarms], this function can save existing alarms to an external disk volume.
- Default file name for exported files
 - Existing alerts alerts Actalm.txt
 - Historical Alerts Alerts Histalm.txt

654			1	and the second se		1Set Kernel	Server	2024/1/30	15:36:14	DEFAULT
GØ1	100%	<u>G1-</u>	G1+	G00	100%	60- 150+	SPD	100%	Sp- Sp+	0.000
				IP Add	ress Parame	ter		1/1		AUTO
IP Addres	ss Setting				Obtain	an IP Address	s via DHCP		T	ICM
IP Addres	55		192.16	8.88.52	Name	Server Parame	ter			JOG
Subnet M	ask		255.25	5.255.0	Primar	DNS		192.168.88.1		Inc JOG
Default G	ateway		192.10	68.88.1	Primar	WINS				MPG
				Net						HOME
					DiskRemote	Host Path				MO
PC Name			SYNTECCNC			ne		PUBLIC		MPG SIM
User Nan	ne				Passw	ord				S.B.K
Net Statu	IS	Code	ode : 1222 The network is unreachable.							
				R	esource Shar	ed				Set Tool
Shared F	older Path		Di	skA\OpenCN	C\NcFiles					Set Drill
				station of the second se	- 100 -		Cycle Stu	Peed Hold	Reset	Alarm
	ve Setting	2 Cancel	F3	CloudAgent		F5 Set Kerne	el F6 With I Setting	Module	F8 OPCU Server	A

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6.7.2. Network settings

654		G0307 NO L1Set Kernel	Server 2024/1/30	15:36:14	DEFAULT			
G01 100%	G1- G1+ G00	100% 60- 60+	SPD 100%	Sp- Sp+	0.000			
	IP Ad	dress Parameter	1/1		AUTO			
IP Address Setting		Obtain an IP Address	via DHCP		MDI			
IP Address	192.168.88.52	Name Server Paramet	er	-	JOG			
Subnet Mask	255.255.255.0	Primary DNS	192,168,88,1					
Default Gateway	192.168.88.1	Primary WINS			MPG			
	Networ	k DiskRemote Host Path			HOME			
PC Name	SYNTECCNC	Dir Name	PUBLIC		M 0 MPG SIN			
User Name		Password			S.B.K			
Net Status	Code : 1222 The network	1222 The network is unreachable.						
	F	Resource Shared			Set Tool			
Shared Folder Path	DiskA\OpenCM	NC/NcFiles			Set Dril			
			Cycle Stort Feed Hold	Reset	Alarm			
F1 Save Setting F2 C	Cancel F3 CloudAgent Setting	F5 Set Kernel Server	F6 With Module Setting	F8 OPCU Server	A (

Path: F5 Maintenance→F2 Network Settings

Description: Set the network connection settings of the system.

Parameter Description

1) How to obtain an IP address

- Please select [Directly specify IP address] when using a jumper.
- When using a network cable, please select [Specify IP address via DHCP], and skip the [IP Location] and [Subnet Mask] settings
- 2 IP address
 - Enter an available IP address within the domain
- 3 Subnet mask
 - Enter the subnet mask for the IP address
- Need to be consistent with the settings on the PC

④ Personal PC name

- Enter the name of the PC to be connected
- Need to be consistent with the settings on the PC
- **5** Shared directory name
 - Enter the name of the folder shared on the PC (needs to be consistent with the settings on the PC)
- 6 User name
 - If the folder shared by the network disk drive is not protected by an account and password, no settings are required. Otherwise, set the corresponding account and password.
- **⑦** User password
 - Same as 「Username」

Core server settings

(54	NcTemp\G0307 N0 L1Set Kernel Server 2024/1/30 15:36:57	DEFAU
G01 100% C1- G	G00 100% C0 60+ SPD 100% C0 60+	DEFAUL
100		0.00 AUTO
	Kernel Server Setting	
		MDI
		JOG
		Inc JO
Start server while boot	•	MPG
TimeOut (milisec)	0	HOME
-		T 1 M Ø
		MPG SI
100 million (1990)		S.B.K
		Main
		Set Too
		Set Dril
	Cheedy hug Cycle Stari Feed Hold Reset	Alarm
	F3 OK F4 Cancel F5 Dipole Log	
< F1 Start Server	F3 OK F4 Cancel F5 Dipole Log	

Path: F5 Maintenance → F2 Network Settings → F5 Core Server

Description: Set core server related functions

Parameter Description

• Whether to start the server when booting

Set whether to start the core server at boot time

• Timeout time (milliseconds)

Sets the acceptable timeout when a connection to the core server fails

Start server

Path: F5 Maintenance \rightarrow F2 Network Settings \rightarrow F5 Core Server \rightarrow F1 Start

Server

Description: Start the core server immediately

6.7.3. Quick diagnosis

G54	and a second	NcTemp\G0307 N	0 L1 Fast Di	ag. 2024/1/30 15:37:19	DEFAULT
601 100%	61- 61+	600 100%	C0- C0+	SPD 100% Sp- Sp+	0.000
System Data	-			1	AUTO
		Billion of Party of P		Sector and and and and	MDI
0.HMI Exe. Times	14512	23.Interpolation %	100	39.CPU Temp.(C)	JOG
1 Motion Intrp. Times	556634	29.MPG Abs. Pos.	0	54.Intrp. Timeout Times 0	Inc JOG
2 PLC San Times	185690	12.DA Voltage	10000	55. Fine Intrp. Timeout Times 0	MPG
3.I/O Scan Times	278287	44.Spindle Cmd.	24000	68 Axis Card Sync. Fail Times 0	HOME
4.Motion Intrp. Run Time	3000	28.Spindle Angle	0	69.Encoder Fdbk. Abnml. Time 0	T 1 M 0
5.PLC Scan Run Time	9000	52.SPD Index Counter	0	70.Encoder Fdbk. Abnml. Value 0	MPG SIM
6.SRAM Write Times	940	13.Tapping Max. Error	0	320 Number of Interpreted Serial Blocks 0	S.B.K
77.HMI Free Memory	301215744	14, Tapping Dyn. Error	0	324 Number of Interpolated Serial Blocks 0	Main
		78 Software Ver.	10,118,50V(build.1)		Set Tool
78.HW. Free Memory	301215744	19.500ware ver.	10.110.004(0000.1)		Set Drill
		Manufa Juni		Frank House Reset	Alarm

Path: F5 Maintenance→F3 Quick Diagnosis **Description:** Display simple diagnostic information of the system.

System information

654	- Transier	NcTemp\G0307 N	0 L1 Fast Di	ag. 2024/1/30	15:37:19	DEFAULT
G01 100%	C1- 61+	G00 100%	GØ- GØ+	SPD 100%	Sp- Sp-	0.000
System Data	-					AUTO
BHMI Exe. Times	14513	23 Interpolation %	100	39.CPU Temp.(C)	mi (P	ICM
	556634	29 MPG Abs. Pos.	0	54 Intrp. Timeout Times	0	JOG
1.Motion Intrp. Times					0	Inc J0
2 PLC San Times	185490	12 DA Voltage	10000	55. Fine Intrp. Timeout Times		MPG
3 I/O Scan Times	278237	44.Spindle Cmd.	24000	68 Axis Card Sync. Fail Times		HOME
4 Mation Intrp. Run Time	3000	28.Spindle Angle	0	69 Encoder Fdbk. Abnml. Time	0	MO
5 PLC Scan Run Time	9000	52.SPD Index Counter	0	70.Encoder Fdbk. Abnml. Value	0	MPG SI
6.SRAM Write Times	940	13.Tapping Max. Error	0	320 Number of Interpreted Serial Blocks	0	5.B.K
77.HMI Free Memory	301215744	14, Tapping Dyn. Error	0	324 Number of Interpolated Serial Blocks		Main
78.HW. Free Memory	301215744	79 Software Ver.	10.118.50V(build.1)		608	Set Too
TO THE MEMORY	301213144					Set Dri
				Cycle Stort Read Holya	Reset	Alarm
	None of the local division of the local divi	F3 Senal PLC				

Path: F5 Maintenance→F3 Quick Diagnosis→F1 System Information **Description:** Display simple diagnostic information of the system and spindle

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Axial information

(54	NcTemp\G0307 N0 L1	Fast Diag.	2024/1/30 15:37:53	
G01 120% CI- GI+	600 100%	CØ- CØ+ SPD	100% Sp-	0.00
				AUT
Controller Axes Data	×		Z	MDI
Absolute Coord	-10000	1814750	10000	J00
Machine Coord.	0	1824750	0	Inc J
Abs. Position Command	-18	1824750	0	
Abs. Position Feedback	-19	1824748	0	MPG
Following Error	0	2	27	Ном
Reasonable Following Error	0	0	0	T
Max. Following Error	75000	75000	13333	MPG S
Index Counter	1582	964586	1601	5.B.
Axis Limit Offset	0	0	0	
Motor Kp Estimation	0	0	0	Mair
Double Loop Abs. Pos. Feedback	0	0	0	Set To
Double Loop Index Counter	0			Set Dr
Double Loop Pos. Error	0		0	
			Share Feed Hold Reset	Alar
				, and the second s

Path: F5 Maintenance→F3 Quick Diagnosis→F2 Axial Information **Description:** Display axial simple diagnostic information

G54				NcTem	ip\GØ	307	NØ L	1 Of	ffset	t/ Se	ettir	ıg	20	24/1	/30		15:3	8:37		DEFAULT
GØ1	100%	G1- G1-	-	G00		100	9%	Ge)-	GØ+		SPD		1	.00%		Sp-	Sp-		0.000
Index	Item	Bar Maria															alue			AUTO
		a share the	Value	F	E	D	C	8	A	9	8	7	6	5	4	3	2	1	0	MDI
3401 3402	The tool magazine lau Tool setting signal typ	NUMBER OF STREET, STREE	MODOO					0		0		0	0	0	0	0	0	0	0	PIDI
3402	Origin type (0. Norma	And and a support of the local division of the local division of the local division of the local division of the	x0007			0		0	0	0	0	0	0	0	0	0	1	1	1	JOG
	Three-axis overtravel	A CONTRACTOR OF	x0007	0		0	0	0	0	0	0	0	0	Ó	0	0	1	1	1	Inc J0
	One-click home search	A MARKAN AND AND A	0x0000	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	
	Inverter alarm (0 Nor	And a second	0x0002	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	0	MPG
	Insufficient air pressu	Construction of the local data	0000x0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	HOME
	Tool setting instrumer	nt (1 Yes O	0x0001	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	T 1
	Total number of tools	in tool mag	0x0008	0	0	0	0	0	0	0	0	0	0	0	0	1	0	0	0	M Ø
	Counter knife signal	(1. Normally	0x0001	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	MPG SI
	The drop from the to	ol setting too	0x0000	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	S.B.K
	The main shaft or ro	A CONTRACTOR OF															0	0	1	Main
	Tool magazine out d			0	0	0	0	0	0	0	U	0	0	0	0	0	0	0		
	Tool magazine back	detection (0		0	0	0	0	0	0	0	0	0	0	0	0	1	0	1	0	Set Too
	Brush detection (0.			0	0	0	0	0	0	0	0	0	0	0	0	1	0	1	0	Set Dril
		用《切》 部項的目的		U	0		, v	Ľ,	, v	Ľ,	Ľ	<u> </u>					and the owner whether the	TAXABLE IN CO.	and the local division of the	Contraction of the second

6.7.4. Extended parameter bits

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Path: F5 Maintenance \rightarrow F4 Extended Parameter Bit.

Explanation

- The controller provides a total of 20 sets of registers R81 ~ R100 for use, each register has a 16Bits setting function.
- These 20 sets of registers can be used to provide control flags for self control of specific PLC functions.
- If the value of the extended parameters (Pr3401 ~ Pr3420) exceeds 0 ~ 65535, the parameter register cannot be set on this screen.

Instructions

(1) Use the direction keys [\uparrow] [\downarrow] [\leftarrow] [\rightarrow] o move the cursor

② Use [PageUp] [PageDown] to switch between the previous and

next pages.

- 3 Only [0] or [1] can be entered.
- ④ Annotations can be made for each bits.
- (5) The string file name corresponding to the annotation is ParamExt_RBit_(L).xml
- 6 (L)=COM/CHT/ Multilingual.

6.7.5. System settings

G54			NcTemp\(50307 NO L1	Parameter	20	24/1/30	15:38:50	DEFAULT
GØ1	100%	G1- G1+	G00	100%	C0- C0+	SPD	100%	Sp- Sp+	0.000
		Iter	n				Value		AUTO
nput/Display			-		R.		0		MDI
System Date S))			2024	1	30	JOG
System Time	Setting (H	H:MM:SS)				15		50	Inc J0
									MPG
									HOME
									T 1 M 0
									MPG SIM
									5.B.K
									Main
									Set Tool
									Set Dril
(0~1)		-				cle Stort	Feed Hold	Reset	Alarm
<s e1="" scree<="" td=""><td>n Adjust</td><td></td><td></td><td></td><td></td><td></td><td>F7 Auto File Cleaner</td><td>F8 Set MM</td><td>liConfig</td></s>	n Adjust						F7 Auto File Cleaner	F8 Set MM	liConfig

Path: F5 Maintenance \rightarrow F5 System Settings.

Description: This function page can be used to set the system environment.

Instructions

- ① Use the direction keys $\uparrow \ \downarrow \ \downarrow \ \downarrow \downarrow \downarrow \downarrow \downarrow \downarrow \downarrow$
- ② Use [PageUp] [PageDown] to switch between the previous and next pages.

Operating mode settings

Explanation

- Set the system to metric or imperial.
 - 00:Metric.
 - 11: imperial.

Note: After setting, you need to restart your computer to take effect.

System time setting

Note: The format for inputting [date _i s YYYY/MM/DD.

- YYYY is the year.
- MM is month.
- DD is day.
- The input format of **time **is HH/MM/SS.
- HH is hour.
- MM is minutes.
- SS is seconds.

6.7.6. Language settings

G54					\G0307 NO L1			024/1/30	15:39:21	DEFAULT
501	100%	G1-	G1+	G00	100%	G0- G0+	SPD	100%	Sp- Sp+	0.000
Index	ltem					Jan Carlos and Carlos		a literation	Value	AUTO
5	*I/O type								100	MDI
9	*Servo type(10								110	10.5
10	*Servo alarm c	_	100	3;2:Disable)	_				1	JOG
15	the I/O board d	igital filt	er method	otor	-		-	×	1	Inc JOG
17	*Control precis		(1:10	put Param N					2	MPG
21	*Port no. for X			put Param N	0.				1000	
22	*Port no. for Y	CHARGE COLOR	2	209					2000	HOME
23	Port no. for Z		3	209	NUMBER OF STREET				4000	T 1 M 0
24	*Port no. for 4t					Ok	Canc	el	3000	MPG SIM
41	X axis motor p								0	
42	Y axis motor p	olarity					distance of the		0	S.B.K
43	Z axis motor po		Charles and			HEIRER			0	Main
44	4th axis motor	ALC: NO.							2500	Set Tool
61	X axis encode		And the second						2500	Set Dril
62	Y axis encode								2500	
63	Z axis encoder	r resoluti	ion(En:p/re	v,RI:p/mm)					2500	
							furth Stor	Feed Hol	Reset	Alarm
							TRACE FOR			
-										
F1.0	K F2	Cancel						and the second		and the second second

Path: F8 parameter list in the main interface \rightarrow F3 parameter list \rightarrow F5 jump to parameter number.

Note: Enter^[3209] to enter the language number that needs to be changed. After confirmation, the system will pop up a security reminder. Enter the password^[520] and click Confirm to complete the modification.

*Note: This interface can not only set the language but also various parameters. Please do not change other parameters. If necessary, please operate under the guidance of technical personnel.



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6.9. Manual tool change

Spindlepindle (T1 T 88)

The air pressure required for tool change is controlled by the pressure regulating valve (the adjustment has been completed by our technical engineers before leaving the factory). The air pressure should be 0.2 0.4MPa and cannot be too high or too low.



In the "main interface", press the spindle brush, raise the brush, and press the green tool change button to change the tool.

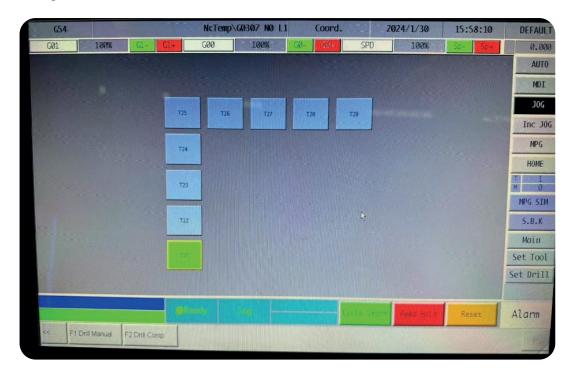
North Produke Attribute 0.000 X 0.000 X 0.000 X 0.000 Y 0.000 Y 0.000 Y 0.000 Y	654 681	100% CL-	61	NC NC 20 100%	NUMBER OF TAXABLE PARTY OF TAXABLE	2024/1/30 SPD 1.00%	15:17:45	DEFAULT 0.000	
Overtravel Rel Y+ Z+ Door Cabinet SP. CW Drill CW Back To Origin Nore Rapid Jog X+ SP. Device Drill Device SP. Cover Set Tool	schilte				0.000		-10.00 -10.00 10.00	AUTO MDI	
Reit Fr. Locate SP. Cover				Door	Management of States	Selection			
X- Rapid Jog X+ SP.Device Drill Device S.B.K Margan	Overtravel Rel.	Y+	Z+	SP. CW	Drill CW		Back To Origin	1 1	
AvenTani Y Z F. Locate SP. Cover Set Tool	X-	Rapid Jog	X+	SP.Device	Drill Device			S.B.K	
	AutoTool	Y-	Z-	F. Locate	SF	.Cover		Set Tool	

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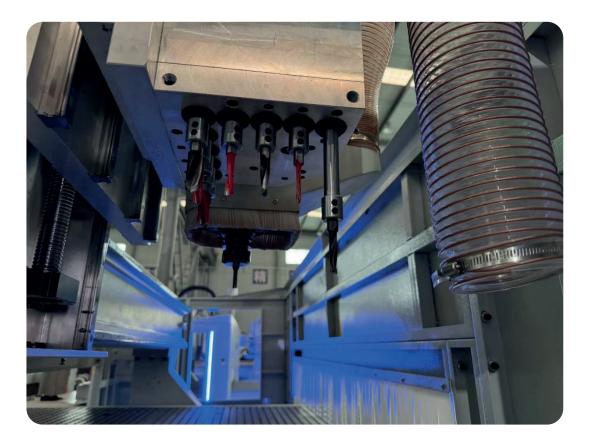
6.10. Drill unit tool change

Drilling unit unit (T21 2929)

Click on the drill row setting on the right side of the main screen to enter the drill row interface, where you can perform operations such as "lowering the designated drill bit".



When disassembling the drill bit, be sure to wear gloves to prevent scratches. Use the hexagonal wrench that comes with the machine to disassemble and assemble.



6.11. Use software to set/change tools (T1-T8)

Method 1: Open the F3 (Offset/Setting) → (Automatic Tool Setting)

Interface

In this interface, you can complete operations such as tool change, tool length measurement, and Z drop setting (only valid for the tool on the current spindle).

TI-T8 are milling cutters; T2I-T29 are row Please pay attention to the spindle tool currently used and avoid repeatedly placing tools on the tool holder, thereby damaging the machine. For example: Tool No. 3 is currently used, and the tool holder No. 3 in the tool magazine should not be placed.

G54				NcTemp	\G0307 NO L1	Coord.		2024/1/30	15:40:24	DEFAULT
G01	100%	G1-	61+	G00	100%	G0- G0+	SPD	100%	So- So+	0.000
uto Tool F	unction			ool No. T		1		Machine		AUTO
lode	3			eedrate F se Reference		400		Х	0.000	MDI
	Single workping			ef Coord. X		1 207.200		Y	1824.750	JOG
	lulti-workpied			ef Coord. Y		3217.000		Z	0.000	Inc Ju
- 17	(Y)	ALCONTRACTOR OF	Track With	ef Coord. Z		-170.000				MPG
1			00/03/02/02	lin. Z Mach. H Safe Z After Me		-270.000 0.000		Relative		
-			10.00	Select if use R		0.000		Х	0.000	HOME
Z	-		1	:Set All measu	ure parameter			Y Z	1824.750 0.000	MO
+	/			to upper of m					0.000	MPG SI
100	<u>P</u>		1	Press F1, Me	asure Start			Aux. Coord.		S.B.K
Delta Z Sel			-11	VorkPiece No.	G54	1				Main
	MZ)o tool tip mea	sure before do l	Delta Z		X Y	0.000	Set Too
			1	Take tool tip	to top of good Ita Z Set			z	0.000	Set Dri
	2 11		In the second	Gauge Air Blov		0 OFF: M	0			
carl							-			Alarm
-20								ort Feed Hold	Reset	ALUIT
.~	art			-3 Z Delta Set	F4 Apply XY Rel	F5 Apply Z Mach	1			

Instructions

- 1. In the knife setting screen, set the \lceil Measurement Mode \rfloor in the upper left corner to 3.
- 2. Enter the target tool number to be calibrated into \lceil Select tool number T_J.

*The following parameters parameters, have been set before the machine leaves the factory. You can use the handwheel guidance mode without modification to directly execute [Automatic tool setting start] to test whether the position has changed. If anything happens during the process, you can press [Automatic tool setting interruption] or emergency stop, stop automatic tool setting, and modify parameters under the guidance of a technical engineer.

3. Set the speed of the first dip and each pull back during automatic tool

setting in $\lceil Measurement\ Speed\ F \rfloor.$

4. Please set \lceil Use reference point coordinates \rfloor to 1, then move the XY axis to align the tool with the center of the tool setter, and press [XY reference point teaching], The confirmation window will pop up and select \lceil Yes \rfloor , The current machine base The mark will automatically fill in \lceil X direction reference point X \rfloor and \lceil Y direction reference point Y \rfloor .

5. Move the cursor to $\lceil Z$ direction reference point Z], and directly set the starting position

of the Z axis downward tool setting, or move the Z axis to the position of the Z direction starting point, and then press [Z axis machine teaching], to set the Z axis. Fill in the axis coordinates with [Z direction reference point Z].

6. Move the cursor to [[]Z axis minimum mechanical coordinate H], use [[]Z axis mechanical teaching []]or directly set the lowest point at which the Z axis can descend during automatic tool setting.

7. After making the above settings, please switch the mode to automatic execution mode and click [F1 to start automatic tool setting], At this time, the system will automatically change the tool to the target tool number, and then start automatic tool setting.

8. If anything happens during the process, you can press [Automatic Tool Setting Interrupt] or emergency stop at any time to stop automatic tool setting.

9. After the automatic tool setting is completed, the Z axis coordinate when the tool tip touches the tool setting instrument will be automatically stored in the specified tool length compensation table.

10. Manually bring the tool tip to any workpiece surface, then set the [¬]drop setting number [¬], press **[**Z axis drop setting **]**, he drop value between the tool presetter and the workpiece surface will be filled in the specified workpiece coordinate system The Z axis coordinate of the workpiece coordinates and the Z axis are now set.

11. Drop setting number:11:G54G54, 22:G55G55, 33:G56G56, 44:G57G57, 55:G58G58, 66: G59G59, 77:G59.1...

12. If there are tool setting requirements for other tool numbers or workpieces, you can also use the MDI mode to complete automatic tool setting for multiple tools and workpieces.

Method 2 (recommended): MDI mode tool change/tool setting (fast multi tool).



Path: F4 Processing Monitor \rightarrow F3 MDI Input (you need to click the "MDI" mode on the right side of the main page first)

Instructions

1. Click the "MDI" mode on the right side of the main page, and then click the "Tool Changing and Tool Setting" button in the "Main Interface" on the right side of the main page (do not press the Tool Changing and Tool Setting key if tool setting is not required).

							JOG
	MLCHint 2 (R59	90.2) Tool char	nge and tool setting	function start pro	ompt		Inc JOG
							MPG
Overtravel							HOME
Rel.						Back To	T I
					1000 Bethe parts	Origin	MPG SIM
X-	Rapid Jog	Χ+	SP.Device	Drill Device			S.B.K
					Common Functions		Main
		Z-	F. Locate		SP.Cover		Set Tool
AutoTool	Y-	2-					Set Drill

* When the tool setting and tool changing function alarm reminder appears, press ESC on the keyboard to close it.

- 2. After entering the tool number T^{**} that requires tool setting and tool change (you can enter multiple) on the keyboard on the right side of the screen, press "FI OK ", and the edited program will be stored in the MDI.
- 3. In "MDI" modemode, click Cycle Start Start, Cycle Start to use the code edited by MDI to perform multi tool tool change/tool setting.



6.12. Set workpiece origin

- 1. First, click "Spindle Brush" in the "Main Interface" to raise the spindle brush.
- 2. Move the tool head to the position on the material surface where processing needs to begin.

3. Open F3 Offset/Setting \rightarrow F1 workpiece coordinate system, use the keyboard to input and use the direction keys $(\uparrow) [\downarrow] [\leftarrow] [\rightarrow]$, move the cursor to the G54 coordinate X axis or click the mouse to select **Workpiece Coordinate** System J Click **F1 Mechanical** Coordinate Teaching], and select **OK**, The X axis workpiece origin is set Move the cursor to the G54 coordinate Y axis and perform the same operation to set the Y axis workpiece origin. (The Z-axis value in the screen is for debugging and cannot be used as a reference).



654			NcTemp	60307 NO L1	Coord.		2024/1/30	15:26:15	DEFAUL
GØ1	190%	G- 01+	G00	100%	60-	SPD	108%	8- 27-	0.00
Extern	al Shift	G54P1	(G54)	G54	P2(G55)		Machine		AUT
x	10.000	x	0.000	x	0.000		Х	0.000	MDI
Ŷ	10,000	1222 Bar	0.000	Ŷ	0.000		Y Z	1824.750 0.000	J00
z	-10.000	Y Z	0.000	Z	0.000		-	0.000	Inc J
	10.000	-	0.000					-	MPO
							Relative		HOM
							X	0.000 1824.750	1
G54P	3(G56)	G54P4	(G57)	G54	P5(G58)		Y Z	0.000	M
x	0.000	x	0.000	x	0.000		100		MPG 5
Ŷ	0.000	Ŷ	0.000	Ŷ	0.000		Aux. Coord.		S.B.
z	0.000	z	0.000	z	0.000		x	0.000	Mai
	0.000		0.000				Y	0.000	Set T
							Z	0.000	Set Dr
			incidy.	5m		Could Ste	Fast Note	Reset	Alar
124	WorkPiece est		Tool Tip	F4 Apply Mach	F5 Apply Rel	F6 Zero	Rel F7 Zero /	Al Rel Law	
Co			easure	Coord	Coord.	Coord	Coord	ar Rel F8 Inc. In	14

Finally, after **F3 Offset/Setting** click **F3 Automatic Tool Setting** and then clicks **F3 Z axis drop setting** the Z axis workpiece coordinate origin setting is completed.

* The Z axis value in the screen is for debugging and cannot be used as a reference. reference.

G54				NcTemp	p\G0307 N0 L1	Coord.		2024/1/30	15:40:24	DEFAULT
GØ1	100%	G1-	61+	G00	100%	G0- G0+	SPD	100%	Sp- Sp+	0.000
uto Tool F	unction		To	ol No. T		1		Machine		AUTO
lode	3			edrate F		400		X	0.000	MDT
	Single work			e Reference		1		Ŷ	1824.750	
Single tool	Multi-workpi	ece		of Coord. X		207.200	-	z	0.000	JOG
:Multi-tool M	lulti-workpie	ce		ef Coord. Y		3217.000			STORES S	Inc J0
e (X.	Y)	A PROPERTY.	W.S. W.S.	ef Coord. Z		-170.000				MPG
				in. Z Mach. H		-270.000		Relative		
Ţ			10.10	afe Z After M		0.000		Х	0.000	HOME
Z				elect if use R				Y	1824.750	T 1 M 0
+ "0	- /		2	If not use Re	sure parameter ef, Take tool tip			Z	0.000	MPG SI
YIGH	~		/	o upper of m	neasurement					6 D. K
			11		easure Start			Aux. Coord.		S.B.K
Delta Z Sel			V	/orkPiece No	o. G54	1		~	0.000	Main
	MZ		D	o tool tip me	asure before do	Delta Z		X	0.000	Set Too
	E PE.6.4		1	Take tool tip Press F3, D	to top of good			Z	0.000	Set Dri
1	INIT		the sector of the sector of the			0 OFF: M	0	-		
carl			C	auge Air Blo	W: ON: M	U OFF.M	0			
				Leady	340			rt Feed Hold	Reset	Alarm
.~3)										
The second second	art	F2 Reset		3 Z Delta Set	F4 Apply XY Re Coord	F5 Apply Z Mach Coord				

6.13. Drilling unit tool setting (T21-29)

Path: F4 Processing Monitor \rightarrow F3 MDI Input (you need to click the "MDI" mode on the right side of the main page first).

Instructions

1. Click the "MDI" mode on the right side of the main page, and then click the "Tool Changing and Tool Setting" button in the "Main Interface" on the right side of the main page (do not press the Tool Changing and Tool Setting key if tool setting is not required).

			Ala		The second s	Contraction of the second s	A CONTRACTOR OF THE OWNER
	MLCHint 2 (R5	90.2) Tool chang	ge and tool setting	function start pro	ompt		Inc JOG
							MPG
Overtravel							HOME
Rel.						Back To	T 1 M 0
						Origin	MPG SIM
Х-	Rapid Jog	Х+	SP.Device	Drill Device			S.B.K
					Common Functions		Main
			(and the second s	COLUMN IN SOME OF STREET	Contributive		Placin
AutoTool	Y-	Z-	F. Locate		SP.Cover		Set Tool

2. After entering the tool number T^{**} that requires tool setting and tool change (you can enter multiple) on the keyboard on the right side of the screen, press ^{[F1} OK] and the edited program will be stored in the MDI Block.

3. In " MDI " mode, click Cycle Start to use the code edited by MDI to perform drilling and tool setting.

8. Basic processing procedures

Boot interface

Press F1 to turn off the alarm. In HOME mode, click Cycle Start. Each axis of the machine will automatically return to the mechanical origin, and the machine tool will immediately start the zero return operation. After the zero return is completed, the pro cessing operation can be carried out out.



* Every time you turn on the machine, you must press the confirmation button to return to the origin, and wait for each axis of the machine to return to the mechanical origin, otherwise the limiter will be ineffective. If it does not return to the origin, the machine will continue to move beyond the maximum stroke, causing safety accidents such as tool breakage or bed damage.

Specific steps

1. Before starting the machine, return all axes to zero.

GØ1	100% G1-	G1+ G0	NC N 0 1009			2024/1/30	15:13:34	DEFA
Ń	Inching					Relative		AL
I\	Aachine	9				X Y Z	544.277 2779.654 -0.140	М
				11 07	7	Ż	-0.140	J
		t back home			4 1000			Inc
		back home						М
4							534.277	HO
							534.277 2769.654 9.860	T. M
								MPG
						Dist. To Go		S.1
i and a second s							0.000	Ма
F	1000.0 mm/min	100 %	S	24000 RPM	100 %	X Y Z	0.000 0.000 0.000	Set
	0.0 mm/min	(Actual)		24000 RPM	(Actual)			Set D
	0 :	0 : 0	Part Count	0	T 1		_	
Run Time	• •						Description	
Run Time		Isady			Cycle Sto	eed Hold	Reset	Ala

2. Perform tool change/tool setting and set the workpiece origin.

G54	and a second			\G0307 NO L1	Coord.		2024/1/30	15:26:15	DEFAU
GØ1	100%	G1- G1+	G00	100%	CO- GO+	SPD	100%	Sp- Sp+	0.00
Exter	nal Shift	G54	P1(G54)	G54	P2(G55)		Machine		TUA
x	10.000	x	0.000	X	0.000		X Y	0.000 1824.750	MD
Y	10.000		0.000	Y	0.000		Z	0.000	JO
z	-10.000		0.000	– Z	0.000				Inc .
							Relative	-	MP
							X	0.000	HOM
							Y	1824.750	T
G54F	P3(G56)	G54	P4(G57)	G54	P5(G58)		Z	0.000	M MPG
x	0.000	x	0.000	X	0.000				5.B
Y	0.000	Y	0.000	Y	0.000		Aux. Coord.		
z	0.000	Z	0.000	Z	0.000		X	0.000	Mai
							Y	0.000	Set T
							Z	0.000	Set D
			Minady	305		Cycle Sto	Feed Hold	Reset	Ala
	1 WorkPiece	F2 Tool Set	F3 Tool Tip Measure	F4 Apply Mach	F5 Apply Rel	F6 Zero Coord	Rel. F7 Zero Coord	All Rel. F8 Inc. Int	out
	ourd.		weasure	Coord	Coord	Coord	Cudid.	Rentances Jewashington	

G54	MC	IBLOCK NO L1	Coord.	2024/1/30	15:47:39	DEFAULT
GØ1 100%	G1- G1+ G00	100% 00-	GØ+ SPD	100%	Sp- Sp+	0.000
External Shift	G54P1(G54)	G54P2(0	355)	Machine		AUTO
X 10.000	Edit Program Name : MDIBloc	MDITInout k Line: 5 Column: 2		X	0.000	MDI
Y 10.000	T2			Z	1824.750 0.000	JOG
Z -10.000	T3 T4					Inc JOG
	and the second se			Relative		MPG
	те				0.000	HOME
				X Y Z	1824.750	T 1 M 0
G54P3(G56)				2	0.000	MPG SIM
X 0.000				Aux. Coord.		5.B.K
Y 0.000	z 0.000	Z	0.000	X	0.000	Main
Z 0.000	2 0.000			1 Y	0.000	Set Too
				Ζ-	0.000	Set Dril
					1000	
	Ready			tort Feed Hold	Reset	Alarm

3. Insert the U disk and click in sequence: F2 program editing \rightarrow F8 file management \rightarrow F4 file transfer \rightarrow F1 file input, click on the file you want to use \rightarrow click copy, press "ESC" to return after completion, check the file location (copy in the root directory, otherwise the file will not be read).

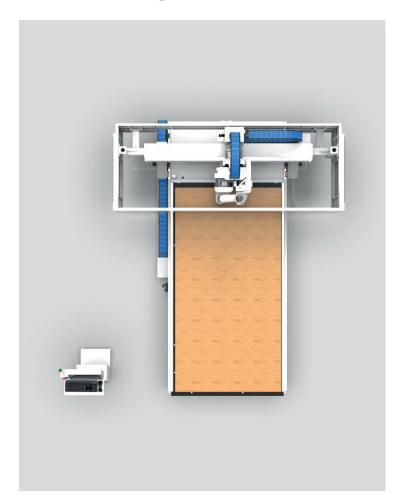
G54		NcTemp	G0307 NO L1	File Manage	er 2024	/1/30 1	5:24:40	DEFAULT
Contraction of the second seco	20% C1- G1+	G00	100%	C0- G0+	SPD	100%	r- Sa	0.00
iskAlOpenCNCINcFile	s Free Space: 3913244KE		Concert and					AUTO
ame	Modified	Comme	nt					MDI
r AutoLabel								
NicTemp MCIBlock	2024/01/29 11:18:00	G00 X0						JOG
	2012/03/20 14 48 22	G00 X0 M98 P9						Inc J
	2017/03/29 10:03:14		0.Y100.Z100.C100					MPG
	2024/01/28 18 57:12 2024/01/28 17 50:16	G54G90 G54G90					ef.	HOME
	2024/01/29 10:36:42	G54G90					14	HUME
	2024/01/29 10:06:48							
						100		MPG SI
								S.B.K
								Main
								Set To
								Set Dri
								in the second
		landy	Jug		vile Start	Feed Hold	Reset	Alarn
< F1 New File	F2 Copy File F3	Delete File	F4 File Transfer	F5 Execute	F6 Select DNC	F7 Folder		
A CONTRACTOR OF A CONTRACTOR O					Fue	Manager		

4. After double-clicking "ESC" to return to the main page, click Cycle Start to run the processing file.

* To ensure the safe and efficient operation of our machinery, please use the handwheel guidance mode for precise adjustments when uncertain. If a problem arises, press the emergency stop button to halt the machine immediately and prevent any potential damage or injury. For operations not covered in this manual or when parameter modifications are necessary, proceed with caution under the guidance of a qualified technical engineer. If you have any questions or need further assistance, our technical support team is available to help you.



9. Machine preview



 This picture is a 3D model, which does not include all buttons, pipelines, vacuum brackets, etc. Please refer to the actual machine



*\$Sta*rProMax | 66





* This picture is a 3D model, which does not include all buttons, pipelines, vacuum brackets, etc. Please refer to the actual machine

10. Equipment maintenance and upkeep

6.14. Maintenance

1) Please do not make any changes without knowledge or authorization about machines, electrical appliances, etc., otherwise it may cause malfunction or damage.

2) Please turn off the power first during maintenance. If live inspection is required, professional electricians are required to perform it.

3) Regularly check whether the emergency stop button is normal

4) Repair and replacement parts must comply with the specifications in the technical documents.

5) The heat dissipation and ventilation system of the CNC device should be cleaned regularly, and the cooling fans on the CNC device should be checked regularly to see if they are working properly. Depending on the general situation of the workshop environment last year, inspection and cleaning should be done every six months or quarterly.

6) Frequently monitor the power supply voltage of the CNC system

7) Prevent dust from entering the CNC device

8) It is important to note that CNC machine tools are not designed for prolonged storage. They should be deployed into production promptly after purchase to prevent any deterioration in performance. Extended periods of inactivity can lead to moisture affecting the electronic components, accelerating their degradation. To maintain the technical integrity of the CNC system during extended idle times, regular maintenance is essential.

6.15. Lubrication and maintenance

- The lubrication cycle depends on the working environment and machine working hours. Generally, the debris should be cleaned up after get off work every day. Lubricate all parts every week (32# lubricating oil) and lubricate high speed idling. Vacuum pump I ubricating oil should be added every 3 months. Please use the designated oil.
- 2) The lubricating oil of the ball screw's cutter screw should be lubricated once a week.
- 3) Spindle lubrication, refuel once a week
- 4) When choosing a lubricant, ensure that the consistency is neither too thick nor too thin. A lubricant that is too dense may hinder mechanical operation, while one that is too light may not offer sufficient protection. Additionally, select a lubricant with low volatility to prevent rapid evaporation or degradation under operational conditions.
- 5) Lubrication part: X and Y axis racks and slide rail sliders. Z axis screw, track slider
- 6) Rack lubrication: Before lubrication, remove the impurities in the rack first. If there are any impurities that cannot be removed, use a sharp object to pick them out, then inject lubricating oil and then gradually increase the speed for idling, that is, do not put the plate, and the three axes Break in.

6.16. Other maintenance

1) The vacuum pump suction filter needs to be cleaned daily to prevent debris from entering the vacuum pump.

2) The vacuum pump outlet filter needs to be cleaned once a week.

3) The degree of contamination of the vacuum pump oil should be tested every two months. If the oil becomes black and sticky, change the oil.

4) Clean the electrical box with an air gun once a week to ensure that the electrical components are not disturbed by dust.

5) The mechanical sliding shaft part should always be kept smooth, with no sawdust or dust impeding its operation.

6) The cooler filter should be cleaned daily to avoid reducing the cooling effect.

7) Please keep the cooling fan filter in the electrical box clean from time to time to prevent dust from entering the electrical box and affecting the performance stability of electrical components.







